Supplementary Material for Energy-Efficient Task Scheduling on Multiple Heterogeneous Computers: Algorithms, Analysis, and Performance Evaluation

Keqin Li, Fellow, IEEE

1 PAPER OUTLINE

The paper is organized as follows. (All section numbers refer to the main paper.) In Section 2, we review related research in energy-efficient heterogeneous computing. In Sections 3-5, we address energyefficient scheduling of independent tasks on multiple heterogeneous computers. In Section 3.1, we define the energy-constrained scheduling problem and develop a method of optimal power allocation for a given schedule, such that the total task execution time is minimized. In Section 3.2, we define the time-constrained scheduling problem and develop a method of optimal power allocation for a given schedule, such that the energy consumption is minimized. The significance of Sections 3.1 and 3.2 is to reduce our scheduling problems to the optimal workload partition problems. In Section 4.1, we develop a method to find an optimal partition of a given workload, such that the total task execution time is minimized. In Section 4.2, we develop a method to find an optimal partition of a given workload, such that the total energy consumption is minimized. The significance of Sections 4.1 and 4.2 is two fold. First, the optimal workload partition can be used to guide us in finding an optimal schedule to solve a scheduling problem. Second, we get lower bounds for the optimal solutions, such that our solutions can be compared with the optimal solutions. In Section 5.1, we describe the MLS algorithm for scheduling independent tasks. In Section 5.2, we give examples of our numerical calculations. In Section 5.3, we present simulation data to demonstrate the performance of our heuristic algorithms.

In Section 6, we address energy-efficient scheduling of precedence constrained tasks on multiple heterogeneous computers. In Section 6.1, we describe the LL- MLS algorithm for scheduling precedence constrained tasks. In Section 6.2, we discuss optimal energy allocation to levels of a dag. In Section 6.3, we discuss optimal time allocation to levels of a dag. The significance of Sections 6.2 and 6.3 is to optimize the performance of the level-by-level scheduling method. In Section 6.4, we present simulation data to demonstrate the performance of our heuristic algorithms. In Section 7, we conclude the paper.

2 HETEROGENEOUS CLOUD COMPUTING

Several authors have incorporated dynamic voltage and frequency scaling into study. In [6], the authors addressed optimal power allocation and load distribution for multiple heterogeneous multicore server processors across clouds and data centers as optimization problems, i.e., power constrained performance optimization and performance constrained power optimization. In [17], the author considered the problem of optimal power allocation among multiple heterogeneous servers in a data center, i.e., minimizing the average task response time of multiple heterogeneous computer systems with energy constraint. In [21], the author investigated the technique of using workload dependent dynamic power management (i.e., variable power and speed of processor cores according to the current workload) to improve system performance and to reduce energy consumption. In [31], the authors optimized the performance and power consumption tradeoff for multiple heterogeneous servers with continuous and discrete speed scaling.

3 NUMERICAL ALGORITHMS

In this section, we give the pseudo-codes of all the numerical algorithms developed in this paper. The classic bisection method, or the binary search algorithm ([5], §2.1, p. 21) is repeatedly used to solve complicated equations. It is a common sense that all meaningful large numbers in the everyday world are

[•] K. Li is with the Department of Computer Science, State University of New York, New Paltz, New York 12561, USA. E-mail: lik@newpaltz.edu

not that large. Consider astronomically large numbers. The estimated number of atoms in the observable universe is only $10^{80} < 2^{266}$. The age of the universe is only 4.355×10^{26} nanoseconds. Since all variables in our study denote real quantities, it is safe to claim that the bisection method can be finished in $O(10^2)$ time. Hence, the bisection method is very efficient. For instance, all the data in Tables 1–2 are produced instantly, while all the data in Tables 5–6 are produced in seconds.

In all our algorithms, the small constant ϵ used to terminate the bisection method is set as 10^{-9} .

Algorithm 4 employs the Gaussian elimination and backward substitution algorithm for solving a linear system of equations ([5], §6.2, p. 265).

Algorithm 7 refers to the following equation from Section 6.3 of the paper:

$$\phi = \sum_{k=1}^{m} \left(\frac{\phi_l}{\alpha_k}\right)^{\alpha_k/(\alpha_k-1)} - \frac{R_l}{T_l} \left(\sum_{k=1}^{m} \frac{1}{\alpha_k(\alpha_k-1)} \left(\frac{\alpha_k}{\phi_l}\right)^{(\alpha_k-2)/(\alpha_k-1)}\right)^{-1} \sum_{k=1}^{m} \left(\frac{1}{\alpha_k-1} \left(\frac{\phi_l}{\alpha_k}\right)^{1/(\alpha_k-1)}\right).$$
(1)

All algorithms are properly cited in the main paper.

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Algorithm 1: Find_ R_k 's $(m, \alpha_1, \alpha_2, ..., \alpha_m, R, E, T)$.

Input: $m, \alpha_1, \alpha_2, ..., \alpha_m, R, E$, and T. Output: $R_1, R_2, ..., R_m$.

//Set W_1 and W_2 (1) $W_0 \leftarrow 1;$ (2) $W_1 \leftarrow W_0;$ (3)do (4) $W_1 \leftarrow W_1/2;$ (5) for $(k \leftarrow 1; k \le m; k++)$ do (6) $R_k \leftarrow T \left(E / \alpha_k W_1 \right)^{1/(\alpha_k - 1)};$ (7)end do; (8)while $(W_1 \ge R_1/\alpha_1 + R_2/\alpha_2 + \dots + R_m/\alpha_m);$ (9) $W_2 \leftarrow W_0;$ (10)do (11) $W_2 \leftarrow 2W_2;$ (12)for $(k \leftarrow 1; k \le m; k++)$ do $R_k \leftarrow T (E/\alpha_k W_2)^{1/(\alpha_k-1)};$ (13)(14)end do; (15)while $(W_2 \le R_1/\alpha_1 + R_2/\alpha_2 + \dots + R_m/\alpha_m);$ (16)//Search W in $[W_1, W_2]$ (17)while $(W_2 - W_1 > \epsilon) / \epsilon$ is a very small constant (18) $W \leftarrow (W_1 + W_2)/2;$ (19)for $(k \leftarrow 1; k \le m; k++)$ do (20) $R_k \leftarrow T \left(E / \alpha_k W \right)^{1/(\alpha_k - 1)};$ (21)end do; (22)if $(R_1/\alpha_1 + R_2/\alpha_2 + \dots + R_m/\alpha_m > W)$ (23) $W_1 \leftarrow W;$ (24)else (25) $W_2 \leftarrow W;$ (26)end if; (27)(28)return $R_1, R_2, ..., R_m$. (29)

Fig. 1. An algorithm to find $R_1, R_2, ..., R_m$.

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Algorithm 2:	Find_	T(m,	α_1, α_2	$\alpha_2,,$	α_m ,	R,	E)
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Input: n	$i, \alpha_1, $	$, \alpha_2,$	$., \alpha_m,$	R,	and	E.
Output:	$R_{1}^{*},$	$R_2^*,$	$, R_m^*$,	an	d <i>T</i> .	

//Set T_1 and T_2	(1)
$T_0 \leftarrow 1;$	(2)
$T_1 \leftarrow T_0;$	(3)
do	(4)
$T_1 \leftarrow T_1/2;$	(5)
Find_ R_k 's($m, \alpha_1, \alpha_2,, \alpha_m, R, E, T_1$);	(6)
while $(R_1 + R_2 + \dots + R_m \ge R)$;	(7)
$T_2 \leftarrow T_0;$	(8)
do	(9)
$T_2 \leftarrow 2T_2;$	(10)
Find_ R_k 's($m, \alpha_1, \alpha_2,, \alpha_m, R, E, T_2$);	(11)
while $(R_1 + R_2 + \dots + R_m \le R)$;	(12)
//Search T in $[T_1, T_2]$	(13)
while $(T_2 - T_1 > \epsilon) / \epsilon$ is a very small constant	(14)
$T \leftarrow (T_1 + T_2)/2;$	(15)
Find_ R_k 's($m, \alpha_1, \alpha_2,, \alpha_m, R, E, T$);	(16)
//The return values are $R_1^*, R_2^*,, R_m^*$	(17)
if $(R_1^* + R_2^* + \dots + R_m^* < R)$	(18)
$T_1 \leftarrow T;$	(19)
else	(20)
$T_2 \leftarrow T;$	(21)
end if;	(22)
end while;	(23)
return $R_1^*, R_2^*,, R_m^*$, and <i>T</i> .	(24)

Fig. 2. An algorithm to find T.

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Algorithm 3: Find_ $E(m, \alpha_1, \alpha_2, ..., \alpha_m, R, T)$.

Input: $m, \alpha_1, \alpha_2, ..., \alpha_m, R$, and T. *Output*: $R_1^*, R_2^*, ..., R_m^*, \phi$, and E.

//Set ϕ_1 and ϕ_2	(1)
$\phi_0 \leftarrow 1;$	(2)
$\phi_1 \leftarrow \phi_0;$	(3)
do	(4)
$\phi_1 \leftarrow \phi_1/2;$	(5)
while $(\sum_{k=1}^{m} (\phi_1 / \alpha_k)^{1/(\alpha_k - 1)} \ge R/T);$	(6)
$\phi_2 \leftarrow \phi_0;$	(7)
do	(8)
$\phi_2 \leftarrow 2\phi_2;$	(9)
while $(\sum_{k=1}^{m} (\phi_2 / \alpha_k)^{1/(\alpha_k - 1)} \le R/T);$	(10)
//Search ϕ in $[\phi_1, \phi_2]$	(11)
while $(\phi_2 - \phi_1 > \epsilon) / \epsilon$ is a very small constant	(12)
$\phi \leftarrow (\phi_1 + \phi_2)/2;$	(13)
if $(\sum_{k=1}^{m} (\phi/\alpha_k)^{1/(\alpha_k - 1)} < R/T)$	(14)
$\phi_1 \leftarrow \phi;$	(15)
else	(16)
$\phi_2 \leftarrow \phi;$	(17)
end if;	(18)
end while;	(19)
for $(k \leftarrow 1; k \le m; k++)$ do	(20)
$R_k^* \leftarrow (\phi/\alpha_k)^{1/(\alpha_k-1)} T;$	(21)
end do;	(22)
$E \leftarrow T \sum_{k=1}^{m} (\phi/\alpha_k)^{\alpha_k/(\alpha_k-1)};$	(23)
return $\overline{R_1^*}, \overline{R_2^*},, \overline{R_m^*}, \phi$, and E .	(24)

Fig. 3. An algorithm to find *E*.

Algorithm 4: Find_ $R'_{l,k}$'s $(m, \alpha_1, ..., \alpha_m, R_l, E_l, \phi)$.

Input: $m, \alpha_1, \alpha_2, ..., \alpha_m, R_l, E_l$, and ϕ . *Output*: $R'_{l,1} + R'_{l,2} + \dots + R'_{l,m}$.

Find_ $T(m, \alpha_1, \alpha_2,, \alpha_m, R_l, E_l)$;	(1)
//The results are $R_{l,1}, R_{l,2},, R_{l,m}$ and T_l	(2)
Solve the system of linear equations in Section 6.2;	(3)
//The results are $R'_{l,1}, R'_{l,2}, \dots, R'_{l,m}$	(4)
return $R'_{l,1} + R'_{l,2} + \dots + R'_{l,m}$.	(5)

Fig. 4. An algorithm to find $R'_{l,1} + R'_{l,2} + \cdots + R'_{l,m}$.

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Algorithm 5: Find_ $E_l(m, \alpha_1, \alpha_2, ..., \alpha_m, R_l, \phi)$.

Input: $m, \alpha_1, \alpha_2, ..., \alpha_m, R_l$, and ϕ . Output: E_l .

//Set E_1 and E_2	(1)
$E_0 \leftarrow 1;$	(2)
$E_1 \leftarrow E_0;$	(3)
while (Find_ $R'_{l k}$'s $(m, \alpha_1,, \alpha_m, R_l, E_1, \phi) < 0$)	(4)
$E_1 \leftarrow E_1/2;$	(5)
end while;	(6)
$E_2 \leftarrow E_0;$	(7)
while (Find_ $R'_{l k}$'s $(m, \alpha_1,, \alpha_m, R_l, E_2, \phi) > 0$)	(8)
$E_2 \leftarrow 2E_2;$	(9)
end while;	(10)
//Search E_l in $[E_1, E_2]$	(11)
while $(E_2 - E_1 > \epsilon) / \epsilon$ is a very small constant	(12)
$E_l \leftarrow (E_1 + E_2)/2;$	(13)
if (Find_ R'_{lk} 's $(m, \alpha_1,, \alpha_m, R_l, E_l, \phi) > 0$)	(14)
$E_1 \leftarrow \tilde{E_l};$	(15)
else	(16)
$E_2 \leftarrow E_l;$	(17)
end if;	(18)
end while;	(19)
return E_l .	(20)

Fig. 5. An algorithm to find E_l .

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Algorithm 6: Min_ $T(m, \alpha_1, ..., \alpha_m, R_1, ..., R_v, E)$.

Input: $m, \alpha_1, \alpha_2, ..., \alpha_m, R_1, R_2, ..., R_v$, and *E*. *Output*: $E_1, E_2, ..., E_v$, and *T*.

//Set ϕ_1 and ϕ_2	(1)
$\phi_0 \leftarrow -1;$	(2)
$\phi_1 \leftarrow \phi_0;$	(3)
do	(4)
$\phi_1 \leftarrow 2\phi_1;$	(5)
for $(l \leftarrow 1; l \le v; l++)$ do	(6)
$E_l \leftarrow \operatorname{Find}_{E_l}(m, \alpha_1,, \alpha_m, R_l, \phi_1);$	(7)
end do;	(8)
while $(E_1 + E_2 + \dots + E_v > E)$;	(9)
$\phi_2 \leftarrow \phi_0;$	(10)
do	(11)
$\phi_2 \leftarrow \phi_2/2;$	(12)
for $(l \leftarrow 1; l \le v; l++)$ do	(13)
$E_l \leftarrow \text{Find}_E_l(m, \alpha_1,, \alpha_m, R_l, \phi_2);$	(14)
end do;	(15)
while $(E_1 + E_2 + \dots + E_v < E)$;	(16)
//Search ϕ in $[\phi_1, \phi_2]$	(17)
while $(\phi_2 - \phi_1 > \epsilon) / \epsilon$ is a very small constant	(18)
$\phi \leftarrow (\phi_1 + \phi_2)/2;$	(19)
for $(l \leftarrow 1; l \le v; l++)$ do	(20)
$E_l \leftarrow \operatorname{Find}_{E_l}(m, \alpha_1,, \alpha_m, R_l, \phi);$	(21)
end do;	(22)
if $(E_1 + E_2 + \dots + E_v < E)$	(23)
$\phi_1 \leftarrow \phi$;	(24)
else	(25)
$\phi_2 \leftarrow \phi$;	(26)
end if;	(27)
end while;	(28)
//Calculate T	(29)
for $(l \leftarrow 1; l \le v; l++)$ do	(30)
Find_ $T(m, \alpha_1, \alpha_2,, \alpha_m, R_l, E_l)$ to get T_l ;	(31)
$T \leftarrow T + T_l;$	(32)
end do;	(33)
return E_1, E_2, \dots, E_n , and T.	(34)

Fig. 6. An algorithm to find $E_1, E_2, ..., E_v$, and T.

Algorithm 7: Find_ $T_l(m, \alpha_1, \alpha_2, ..., \alpha_m, R_l, \phi)$.

Input: $m, \alpha_1, \alpha_2, ..., \alpha_m, R_l$, and ϕ . *Output*: T_l .

//Set T_1 and T_2 (1) $T_0 \leftarrow 1;$ (2) $T_1 \leftarrow T_0;$ (3)(4)do $T_1 \leftarrow T_1/2;$ (5) Find_ $E(m, \alpha_1, \alpha_2, ..., \alpha_m, R_l, T_1)$ to get ϕ_l ; (6) while (the right-hand side of Eq. (1) > ϕ); (7) $T_2 \leftarrow T_0;$ (8)do (9) $T_2 \leftarrow 2T_2;$ (10)Find_ $E(m, \alpha_1, \alpha_2, ..., \alpha_m, R_l, T_2)$ to get ϕ_l ; (11)while (the right-hand side of Eq. (1) $< \phi$); (12)//Search T in $[T_1, T_2]$ (13)while $(T_2 - T_1 > \epsilon) / \epsilon$ is a very small constant (14) $T_l \leftarrow (T_1 + T_2)/2;$ (15)Find_ $E(m, \alpha_1, \alpha_2, ..., \alpha_m, R_l, T_l);$ (16)if (the right-hand side of Eq. (1) $< \phi$); (17) $T_1 \leftarrow T_l;$ (18)else (19) $T_2 \leftarrow T_l;$ (20)end if; (21)end while; (22)return T_l . (23)

Fig. 7. An algorithm to find T_l .

Algorithm 8: Min_ $E(m, \alpha_1, ..., \alpha_m, R_1, ..., R_v, T)$.

Input: $m, \alpha_1, \alpha_2, ..., \alpha_m, R_1, R_2, ..., R_v$, and *E*. *Output*: $T_1, T_2, ..., T_v$, and *E*.

//Cat / and /	(1)
//Set ϕ_1 and ϕ_2	(1)
$\phi_0 \leftarrow -1;$	(2)
$\phi_1 \leftarrow \phi_0;$	(3)
do	(4)
$\phi_1 \leftarrow 2\phi_1;$	(5)
for $(l \leftarrow 1; l \le v; l++)$ do	(6)
$T_l \leftarrow \text{Find}_T(m, \alpha_1,, \alpha_m, R_l, \phi_1);$	(7)
end do;	(8)
while $(T_1 + T_2 + \dots + T_v > T);$	(9)
$\phi_2 \leftarrow \phi_0;$	(10)
do	(11)
$\phi_2 \leftarrow \phi_2/2;$	(12)
for $(l \leftarrow 1; l < v; l++)$ do	(13)
$T_l \leftarrow \text{Find } T_l(m, \alpha_1, \dots, \alpha_m, R_l, \phi_2)$:	(14)
end do:	(15)
while $(T_1 + T_2 + \dots + T_n < T)$;	(16)
//Search ϕ in $[\phi_1, \phi_2]$	(17)
while $(\phi_2 - \phi_1 > \epsilon) / \epsilon$ is a very small constant	(18)
$\phi \leftarrow (\phi_1 + \phi_2)/2;$	(19)
for $(l \leftarrow 1; l < v; l++)$ do	(20)
$T_l \leftarrow \operatorname{Find}_{T_l}(m, \alpha_1,, \alpha_m, R_l, \phi);$	(21)
end do;	(22)
if $(T_1 + T_2 + \dots + T_v < T)$	(23)
$\phi_1 \leftarrow \phi$;	(24)
else	(25)
$\phi_2 \leftarrow \phi_i$	(26)
end if:	(27)
end while:	(28)
//Calculate E	(20)
for $(l \leftarrow 1; l \le v; l++)$ do	(2)
Find $E(m, \alpha_1, \alpha_2, \dots, \alpha_n, B, T_i)$ to get E_i :	(30)
$E \sqsubseteq E \bot E_i$	(31)
$D = D + D_l$,	(32)
	(33)
return I_1, I_2, \dots, I_v , and E.	(34)

Fig. 8. An algorithm to find $T_1, T_2, ..., T_v$, and E.